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NON-SINGULAR SPACETIMES WITH A NEGATIVE COSMOLOGICAL CONSTANT: II. STATIC SOLUTIONS OF THE EINSTEIN-MAXWELL EQUATIONS

PIOTR T. CHRUŚCIEL AND ERWANN DELAY

ABSTRACT. We construct infinite-dimensional families of non-singular static space times, solutions of the vacuum Einstein-Maxwell equations with a negative cosmological constant. The families include an infinite-dimensional family of solutions with the usual AdS conformal structure at conformal infinity.

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1. Introduction

A class of spacetimes of interest is that of metrics satisfying the Einstein-Maxwell equations with a negative cosmological constant and admitting a smooth conformal completion at infinity. It is natural to seek for static solutions with this property. In this paper we show that a large class of such fields can be constructed by prescribing the conformal class of a static Lorentzian metric and the asymptotic behaviour of the electric field on the conformal boundary $\partial \mathcal{M}$, provided that the boundary class is sufficiently close to, e.g., that of anti-de Sitter spacetime and the freely prescribable leading coefficient in an asymptotic expansion of the electric potential is sufficiently small. This complements our previous work on vacuum metrics in [7], which we think of as paper I in this series.

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The key new difference of the current result, as compared to [3, 4, 7], is that we can drive the solution with the electric field maintaining, if desired, a conformally flat structure at the conformal boundary at infinity.

We thus seek to construct Lorentzian metrics g, solutions of Einstein-Maxwell equations with a negative cosmological constant Λ , in any spacedimension $n \geq 3$. More precisely, we consider the following field equations for a metric

$$\mathbf{g} = g_{\mu\nu} dx^{\mu} dx^{\nu}$$

and a two-form field F in space-time dimension n+1, $n\geq 3$ generalising the Einstein-Maxwell equations in dimension 3 + 1 as

(1.1)
$$\operatorname{Ric}(\mathbf{g}) - \frac{\operatorname{Tr}\operatorname{Ric}(\mathbf{g})}{2}\mathbf{g} + \Lambda\mathbf{g} = F \circ F - \frac{1}{4}\langle F, F \rangle_{\mathbf{g}}\mathbf{g},$$

where Tr denotes a trace with the relevant metric (which should be obvious from the context), $(F \circ F)_{\alpha\beta} := g^{\mu\nu} F_{\alpha\mu} F_{\beta\nu}$, and

$$\langle F, F \rangle \equiv g^{\alpha\beta} g^{\mu\nu} F_{\alpha\mu} F_{\beta\nu} =: |F|^2.$$

This is complemented with the Maxwell equations

$$\operatorname{div}_{\mathbf{g}} F = 0 = dF.$$

We further assume existence of a hypersurface-orthogonal globally timelike Killing vector $X = \partial/\partial t$. In adapted coordinates the space-time metric can be written as

(1.3)
$$\mathbf{g} = -V^2 dt^2 + \underbrace{g_{ij} dx^i dx^j}_{=g},$$
(1.4)
$$\partial_t V = \partial_t g = 0.$$

$$\partial_t V = \partial_t g = 0.$$

We further assume that the Maxwell field takes the form

(1.5)
$$F = d(Udt), \quad \partial_t U = 0.$$

Our main result reads as follows (see Section 2 below for the definition of non-degeneracy; the function ρ in (1.7) is a coordinate near the conformal boundary at infinity ∂M that vanishes at ∂M):

Theorem 1.1. Let $n = \dim M \geq 3$, $k \in \mathbb{N} \setminus \{0\}$, $\alpha \in (0,1)$, and consider an Einstein metric $\mathring{\mathbf{g}}$ as in (1.3)-(1.4) with strictly positive $V = \mathring{V}$, $g = \mathring{g}$, such that the associated Riemannian metric $\mathring{\mathfrak{g}} = \mathring{V}^2 d\varphi^2 + \mathring{\mathfrak{g}}$ on $\mathbb{S}^1 \times M$ is C^2 -compactifiable and non-degenerate, with smooth conformal infinity. For every smooth \hat{U} , sufficiently close to zero in $C^{k+2,\alpha}(\partial M)$, there exists a unique, modulo diffeomorphisms which are the identity at the boundary, solution of the static Einstein-Maxwell equations of the form (1.3)-(1.5) such that, in local coordinates near the conformal boundary ∂M ,

(1.6)
$$V - \mathring{V} = O(\rho), \quad g_{ij} - \mathring{g}_{ij} = O(1),$$

(1.7)
$$U = \widehat{U} + \begin{cases} O(\rho), & n = 3; \\ O(\rho^2 \ln \rho), & n = 4; \\ O(\rho^2), & n \ge 5. \end{cases}$$

REMARK 1.2. We have emphasised the freedom to choose the leading-order behaviour \hat{U} of U. As such, the leading-order behaviour of both \mathring{V} and \mathring{q} is, similarly, freely prescribable near a non-degenerate solution [4,7]. Here one can, if desired, proceed in two steps: first, find the static solution with new fields V and \mathring{q} near a non-degenerate solution; small such perturbations will preserve non-degeneracy. One can then use Theorem 1.1 at the perturbed static solution to obtain a new \hat{U} .

The (n + 1)-dimensional anti-de Sitter metric is non-degenerate in the sense above (see eg. [4] appendix D), so Theorem 1.1 provides in particular an infinite dimensional family of solutions near that metric. We note existence of further large classes of Einstein metrics satisfying the non-degeneracy condition [1, 2, 4, 13].

The requirement of strict positivity of V excludes black hole solutions, we are hoping to return to this question in a near future. In fact, this work was prompted by [12], where static Einstein-Maxwell black holes solutions driven by the asymptotics of the electric field have been discovered numerically.

Similarly to [12], for generic \hat{U} the resulting space-time metric will have no isometries other than time-translations.

When the free boundary data \widehat{U} are smooth and when $\mathring{\mathfrak{g}}$ is conformally smooth, the solutions constructed here will have a polyhomogeneous expansion at the conformal boundary at infinity. The proof of this is an immediate repetition of the argument presented in [7, Section 7], where the reader can also find the definition of polyhomogeneity. The decay rates in (1.6)-(1.7) have to be compared with the local-coordinates leading-order behavior ρ^{-2} both for \mathring{V}^2 and \mathring{g}_{ij} . A more precise version of (1.6)-(1.7) in terms of weighted function spaces (we follow the notation in [7, 13]) reads, in all dimensions,

(1.8)
$$(V - \mathring{V}) \in C_1^{k+2,\alpha}(M), \ (g - \mathring{g}) \in C_2^{k+2,\alpha}(M, \mathcal{S}_2),$$
(1.9)
$$U - \widehat{U} \in C_1^{k+2,\alpha}(M),$$

$$(1.9) U - \widehat{U} \in C_1^{k+2,\alpha}(M)$$

and the norms of the differences above are small in those spaces. To this one can add, in dimensions $n \geq 4$,

(1.10)
$$U - \hat{U} - U_{\ln \rho^2} \ln \rho \in C_2^{k+2,\alpha}(M),$$

with the function $U_{\text{ln}} \in C^{\infty}(\mathbb{S}^1 \times \overline{M})$ given by (5.4) below when n = 4, and $U_{\rm ln} \equiv 0$ in dimension $n \geq 5$. Interestingly enough, in dimension n = 4 the function $U_{\rm ln}$ vanishes only when $dU \equiv 0$, hence the space-time is vacuum, see Remark 5.3 below.

The proof of Theorem 1.1 can be found at the end of Section 5. It follows closely [7], and proceeds through an implicit-function argument, with the key isomorphism properties of the associated linearised operator borrowed from [7, 13], and presented in Section 3.

We note that a constant \widehat{U} implies vacuum, by uniqueness of solutions. Hence the energy density of the Maxwell field behaves as ρ^4 for small ρ if not identically zero (cf. (A.14) below), which leads to finite-total-energy configurations in space-dimensions n=3 and 4, but infinite matter energy in higher dimensions.

2. Definitions, notations and conventions

Our definitions and conventions are identical to those in [7, Section 2]. Here we simply recall that the Lichnerowicz Laplacian acting on a symmetric two-tensor field is defined as $[6, \S 1.143]$

$$\Delta_L h_{ij} = -\nabla^k \nabla_k h_{ij} + R_{ik} h^k{}_j + R_{jk} h^k{}_i - 2R_{ikjl} h^{kl}.$$

The operator $\Delta_L + 2n$ arises naturally when linearising the equation

(2.1)
$$\operatorname{Ric}(\mathfrak{g}) = -n\mathfrak{g},$$

where $Ric(\mathfrak{g})$ is the Ricci curvature of \mathfrak{g} , at a solution. We will say that a metric is non-degenerate if $\Delta_L + 2n$ has no L^2 -kernel.

3. Isomorphism theorems

In this section we recall two isomorphism results from [7, Section 3] and prove an isomorphism theorem on scalars, as needed in the remainder of this work. The reader might also want to consult the introductory comments in [7, Section 3], which remain valid in the current context.

3.1. An isomorphism on two-tensors. We will need [7, Corollary 3.2]:

COROLLARY 3.1. Let $(\mathbb{S}^1 \times M, V^2 d\varphi^2 + g)$ be an asymptotically hyperbolic non-degenerate Riemannian manifold with $\partial_{\varphi}V = 0 = \partial_{\varphi}g$. Consider the map

$$(W,h) \mapsto (l(W,h), L(W,h)),$$

where

(3.1)
$$l(W,h) = V \left[(\nabla^* \nabla + 2n + V^{-1} \nabla^* \nabla V + V^{-2} | dV |^2) W + V^{-1} \nabla_i V \nabla^j W - V^{-1} \nabla^j V \nabla^k V h_{kj} + \langle \operatorname{Hess}_q V, h \rangle_q \right],$$

and

$$(3.2) L_{ij}(W,h) = \frac{1}{2}\Delta_L h_{ij} + nh_{ij} - \frac{1}{2}V^{-1}\nabla^k V \nabla_k h_{ij}$$

$$+ \frac{1}{2}V^{-2}(\nabla_i V \nabla^k V h_{kj} + \nabla_j V \nabla^k V h_{ki})$$

$$- \frac{1}{2}V^{-1}(\nabla_i \nabla^k V h_{kj} + \nabla_j \nabla^k V h_{ki})$$

$$+ 2V^{-2}W(\operatorname{Hess}_q V)_{ij} - 2V^{-3}\nabla_i V \nabla_j V W.$$

Then (l,L) is an isomorphism from $C_{\delta-1}^{k+2,\alpha}(M) \times C_{\delta}^{k+2,\alpha}(M,\mathcal{S}_2)$ to $C_{\delta-2}^{k,\alpha}(M) \times C_{\delta}^{k,\alpha}(M,\mathcal{S}_2)$ when $\delta \in (0,n)$.

3.2. **An isomorphism on one-forms.** We will also need [7, Corollary 3.5]:

COROLLARY 3.2. Let $k \in \mathbb{N}$, $\alpha \in (0,1)$. Under the hypotheses of Corollary 3.1, suppose moreover that the Ricci tensor of $V^2d\varphi^2 + g$ is negative. Consider the operator

$$\Omega_i \mapsto B(\Omega)_i + R_{ij}\Omega^j - V^{-1}\nabla_i\nabla^j V\Omega_j =: \mathcal{B}(\Omega)_i$$

where

$$B(\Omega)_i := \nabla^k \nabla_k \Omega_i + V^{-1} \nabla^k V \nabla_k \Omega_i - V^{-2} \nabla_i V \nabla^k V \Omega_k.$$

Then \mathcal{B} is an isomorphism from $C_{\delta}^{k+2,\alpha}(M,\mathcal{T}_1)$ to $C_{\delta}^{k,\alpha}(M,\mathcal{T}_1)$ when $|\delta - \frac{n}{2}| < \sqrt{\frac{n^2}{4} + 1}$.

3.3. An isomorphism on functions. If we assume that $V^2d\varphi^2 + g$ is a static asymptotically hyperbolic metric on $\mathbb{S}^1 \times M$, then it is easy to check that

(3.3)
$$V^{-2}|dV|^2 \to 1 \text{ and } V^{-1}\nabla^i\nabla_iV \to n$$

as the conformal boundary is approached. We will need an isomorphism property for the following operator acting on functions with s = -1; in [7] the result has already been established with s = -3 and s = 3, so for future reference it appears useful to consider all values of s:

$$\sigma \mapsto \mathcal{T}_s \sigma := V^{-s} \nabla^i (V^s \nabla_i \sigma) = \nabla^i \nabla_i \sigma + s V^{-1} \nabla^i V \nabla_i \sigma.$$

THEOREM 3.3. Let (M,g) be an n-dimensional Riemannian manifold with an asymptotically hyperbolic metric with V > 0 and assume that (3.3) holds. Let $s \neq 1 - n$ and suppose that

$$\frac{s+n-1-|s+n-1|}{2}<\delta<\frac{s+n-1+|s+n-1|}{2}\,.$$

If $s \geq -\frac{n-1}{2}$ then \mathcal{T}_s is an isomorphism from $C_{\delta}^{k+2,\alpha}(M)$ to $C_{\delta}^{k,\alpha}(M)$. If $s < -\frac{n-1}{2}$, then \mathcal{T}_s is an isomorphism from $C_{\delta}^{k+2,\alpha}(M)/\mathbb{R}$ to

(3.4)
$$\left\{ \sigma \in C^{k,\alpha}_{\delta}(M) : \int_{M} V^{s} \sigma = 0 \right\}.$$

Proof. When s+n-1>0, we can use [5, Theorem 7.2.1 (ii) and Remark (i), p. 77] to conclude. As we want the result for any $s\neq 1-n$, for the remaining cases we appeal to the results of Lee [13]. For this we need a formally self-adjoint operator, so we set $\sigma=V^{-\frac{s}{2}}f$, thus

$$\mathcal{T}_s \sigma = V^{-\frac{s}{2}} \left[\nabla^i \nabla_i f - \frac{s}{2} \left((\frac{s}{2} - 1) V^{-2} |dV|^2 + V^{-1} \nabla^i \nabla_i V \right) f \right] =: V^{-\frac{s}{2}} T_s f.$$

By assumption $V^{-2}|dV|^2 \to 1$ and $V^{-1}\nabla^i\nabla_i V \to n$ at the conformal boundary, leading to the following indicial exponents for T_s :

$$\delta = \frac{n-1 \pm |s+n-1|}{2} \,.$$

We want to show that T_s satisfies condition (1.4) of [13],

$$||u||_{L^2} \le C||T_s u||_{L^2},$$

for smooth u compactly supported in a sufficiently small open set $\mathcal{U} \subset M$ such that $\overline{\mathcal{U}}$ is a neighborhood of ∂M . Let us recall the following, well known result (see eg. [7, Lemma 3.8]):

Lemma 3.4. On an asymptoically hyperbolic manifold (M, g) with boundary defining function ρ we have, for all compactly supported C^2 functions,

$$\int u \nabla^* \nabla u \ge \left(\frac{n-1}{2}\right)^2 \int (1 + O(\rho))u^2.$$

Lemma 3.4 combined with the hypothesis (3.3) shows that

$$||u||_{L^2}||T_s u||_{L^2} \ge -\int uT_s u \ge \int \left(\frac{(n-1)^2}{4} + \frac{s}{2}(\frac{s}{2} + n - 1) + o(1)\right)u^2,$$

from which it follows that T_s satisfies indeed (3.6) with

$$C^{-1} = \frac{(s+n-1)^2}{4} \,.$$

We recall that the critical fall-off for a function to belong to L^2 is $O(\rho^{\frac{n-1}{2}})$. This can be used to show that the L^2 -kernel of T_s equals

$$\ker T_s = V^{\frac{s}{2}} \mathbb{R} \cap L^2 = \left\{ \begin{array}{l} \{0\} \text{ if } s \geq -\frac{n-1}{2} \,, \\ V^{\frac{s}{2}} \mathbb{R} \text{ if } s < -\frac{n-1}{2} \,. \end{array} \right.$$

Indeed, assume that f is in the L^2 -kernel of T_s . By elliptic regularity (see [13, Lemma 4.8] for instance) f is H^2 on M. This implies in particular that no boundary terms arise in the following integration by parts:

$$0 = -\int f T_s f = -\int f V^{-\frac{s}{2}} \nabla^i [V^s \nabla_i (V^{-\frac{s}{2}} f)]$$
$$= \int V^s |\nabla (V^{-\frac{s}{2}} f)|^2.$$

So $V^{-\frac{s}{2}}f$ is a constant. Using [13], Theorem C(c), we find:

- If $s \geq \frac{n-1}{2}$ then the kernel (and then the cokernel) of T_s is trivial so T_s is an isomorphism from $C_{\delta-\frac{s}{2}}^{k+2,\alpha}(M)$ to $C_{\delta-\frac{s}{2}}^{k,\alpha}(M)$.
- If $s < -\frac{n-1}{2}$, then T_s is an isomorphism from $C_{\delta-\frac{s}{2}}^{k+2,\alpha}(M)/V^{s/2}\mathbb{R}$ to the orthogonal to the kernel:

$$\left\{ f \in C^{k,\alpha}_{\delta - \frac{s}{2}}(M) : \int_M V^{s/2} f = 0 \right\}.$$

The conclusion follows for \mathcal{T}_s if we recall that $\sigma = V^{-\frac{s}{2}}f$ is in $C^{k,\alpha}_\delta(M)$ iff $f \in C^{k,\alpha}_{\delta-\frac{s}{2}}(M)$.

4. The equations

Rescaling the metric to achieve a convenient normalisation of the cosmological constant,

(4.1)
$$\Lambda = -\frac{n(n-1)}{2},$$

the vacuum Einstein-Maxwell equations for a metric satisfying (1.3)-(1.4) read (see Appendix A)

$$(4.2) \begin{cases} V(\nabla^* \nabla V + nV) = -\frac{n-2}{n-1} |dU|_g^2, \\ \operatorname{Ric}(g) + ng - V^{-1} \operatorname{Hess}_g V = V^{-2} \left(-dU \otimes dU + \frac{1}{n-1} |dU|_g^2 g \right), \\ \operatorname{div}_g(V^{-1} \nabla U) = 0. \end{cases}$$

4.1. The linearised equation. We use the symbol Tr, or Tr_g when the metric could be ambiguous, to denote the trace. As in [7] we set

grav
$$h = h - \frac{1}{2} \operatorname{Tr}_g hg$$
, $(\operatorname{div} h)_i = -\nabla^k h_{ik}$, $(\operatorname{div}^* w)_{ij} = \frac{1}{2} (\nabla_i w_j + \nabla_j w_i)$,

(note the geometers' convention, in which we have a negative sign in the definition of divergence). We consider the operator from the set of functions times symmetric two tensor fields to itself, defined as

$$\begin{pmatrix} V \\ g \end{pmatrix} \mapsto \begin{pmatrix} V(\nabla^* \nabla V + nV) \\ \operatorname{Ric}(g) + ng - V^{-1} \operatorname{Hess}_g V \end{pmatrix} .$$

(To avoid ambiguities, $\nabla^* \nabla \equiv -\nabla^i \nabla_i =: -\Delta$.) The two components of its linearisation at (V, g) are

$$p(W,h) = V \left[(\nabla^* \nabla + 2n + V^{-1} \nabla^* \nabla V)W + \langle \operatorname{Hess}_g V, h \rangle_g - \langle \operatorname{div} \operatorname{grav} h, dV \rangle_g \right],$$

$$P_{ij}(W,h) = \frac{1}{2} \Delta_L h_{ij} + nh_{ij} + \frac{1}{2} V^{-1} \nabla^k V (\nabla_i h_{kj} + \nabla_j h_{kj} - \nabla_k h_{ij}) - (\operatorname{div}^* \operatorname{div} \operatorname{grav} h)_{ij} + V^{-2} W (\operatorname{Hess}_g V)_{ij} - V^{-1} (\operatorname{Hess}_g W)_{ij}.$$

It turns out to be convenient to introduce the one-form

$$w_j = V^{-1} \nabla^k V h_{kj} + \nabla^k h_{kj} - \frac{1}{2} \nabla_j (\operatorname{Tr} h) - V^{-1} \nabla_j W - V^{-2} \nabla_j V W,$$

which allows us to rewrite P(W, h) as

$$P(W,h) = L(W,h) + \operatorname{div}^* w$$

where L is as in Corollary 3.1. Similarly, p(W, h) can be rewritten as

$$p(W,h) = l(W,h) + V\langle w, dV \rangle_a$$

with l given by (3.1).

4.2. The modified equation. In Section 5 we will use the implicit function theorem to construct our solutions, using the observation of [10], how to obtain a well-behaved equation by adding "gauge fixing terms". We choose those terms as in [7], appealing to harmonic maps for the vacuum Einstein equations in one dimension higher.

Indeed, we will be solving the following system of equations

$$\begin{aligned} \text{(4.3)} \qquad & \left\{ \begin{array}{l} V(\nabla^*\nabla V + nV + \langle \Omega, dV \rangle) + \frac{n-2}{n-1}|dU|_g^2 = 0 \,, \\ \operatorname{Ric}(g) + ng - V^{-1} \operatorname{Hess}_g V + \operatorname{div}^* \Omega \\ -V^{-2} \left(-dU \otimes dU + \frac{1}{n-1}|dU|_g^2 g \right) = 0 \,, \\ \operatorname{div}_g(V^{-1}\nabla U) = 0 \,, \end{array} \right. \end{aligned}$$

where

$$(4.4) \quad -\Omega_{j} \quad \equiv \quad -\Omega(V, g, \mathring{V}, \mathring{g})_{j}$$

$$:= \quad \mathfrak{g}_{j\mu}\mathfrak{g}^{\alpha\beta}(\Gamma(\mathfrak{g})^{\mu}_{\alpha\beta} - \Gamma(\mathring{\mathfrak{g}})^{\mu}_{\alpha\beta})$$

$$= \quad g^{\ell m}(\mathring{\nabla}_{m}g_{j\ell} - \frac{1}{2}\mathring{\nabla}_{j}g_{\ell m}) + V^{-2}g_{jk}(\mathring{V}\mathring{\nabla}^{k}\mathring{V} - V\nabla^{k}V),$$

where $\mathring{\nabla}$ -derivatives are relative to the metric \mathring{g} , with Christoffel symbols $\mathring{\Gamma}^{\alpha}_{\beta\gamma}$, latin indices run from 0 to n, and $\mathfrak{g} := V^2(dx^0)^2 + g$ with Christoffel symbols $\Gamma(\mathfrak{g})^{\alpha}_{\beta\gamma}$, while the $\Gamma(\mathring{\mathfrak{g}})^{\alpha}_{\beta\gamma}$'s are the Christoffel symbols of the metric $\mathring{\mathfrak{g}}$.

The derivative of Ω with respect to (V,g) at $(\mathring{V},\mathring{g})$ is

$$D_{(V,g)}\Omega(\mathring{V},\mathring{g},\mathring{V},\mathring{g})(W,h) = -w,$$

where w is the one-form defined in Section 4.1 with (V, g) replaced with $(\mathring{V}, \mathring{g})$. Thus, the linearisation of (q, Q) at $(\mathring{V}, \mathring{g})$ is

$$D(q,Q)(\mathring{V},\mathring{q}) = (l,L),$$

where (l, L) is the operator defined in Section 4.1 with (V, g) replaced with $(\mathring{V}, \mathring{g})$. We will show that, under reasonable conditions, solutions of (4.3) are solutions of (4.2)).

PROPOSITION 4.1. If (U, V, g) solves (4.3) then Ω is in the kernel of \mathcal{B} . If moreover $\Omega \in C^{2,\alpha}_{\delta}$ for some $\delta > n/2 - \sqrt{1 + n^2/4}$, then $\Omega \equiv 0$, so that (U, V, g) solves (4.2).

Proof. A standard adaptation of the argument in [7] gives the result; we sketch this for completeness. Set

$$a := -\frac{n-2}{n-1}V^{-2}|dU|^2,$$

$$A := V^{-2}(-dU \otimes dU + \frac{1}{n-1}|dU|^2g).$$

With this notation, the first two equations in (4.3) take the form

$$\begin{cases} \nabla^* \nabla V + nV + \langle \Omega, dV \rangle = Va , \\ \operatorname{Ric}(g) + ng - V^{-1} \operatorname{Hess}_g V + \operatorname{div}^* \Omega = A , \end{cases}$$

The tensor field $E(g) = \operatorname{grav}_g \operatorname{Ric}(g)$, has vanishing divergence, which provides the equation $\mathcal{B}(\Omega) = 0$ for Ω . Indeed, the operator $\mathcal{B}(\Omega)$ defined above has been constructed in [7] so that it vanishes when the modified equation for the metric holds and when the Lorentzian (n+1)-dimensional divergence of the (n+1)-dimensional energy-momentum tensor vanishes. The latter condition is satisfied when the (n+1)-dimensional matter field equations hold; in the current case, this coincides with the last equation in (4.3).

An alternative, n-dimensional argument proceeds as follows: The calculation following [7, Equation (4.6)] shows that for a solution to the modified equation, the divergence of E(g) equals

$$0 \equiv \operatorname{div} E(g) = \frac{1}{2}\mathcal{B}(\Omega) + \beta,$$

where

(4.6)
$$\beta := V^{-1}d(Va) - V^{-1}A(\nabla V, .) + \operatorname{div}(\operatorname{grav}_g A + \frac{a}{2}g).$$

The vanishing of β can be checked by a somewhat lengthy calculation using (4.3).

Either way, the Bianchi identity $\operatorname{div} E(g) = 0$ shows that Ω is in the kernel of \mathcal{B} . It follows from Corollary 3.2 that the only solution of this equation which decays as described is zero.

For future reference we consider the static equations, modified as in (4.5), with a general energy-momentum tensor:

$$(4.7) - V^{-1}\nabla^{i}\nabla_{i}V - \frac{2\Lambda}{n-1} + V^{-1}\nabla^{i}\Omega\nabla_{i}V = \underbrace{-T_{\alpha\beta}N^{\alpha}N^{\beta} - \frac{g^{\alpha\beta}T_{\alpha\beta}}{n-1}}_{=:a},$$

$$(4.8) R_{ij} - V^{-1} \nabla_i \nabla_j V - \frac{2\Lambda}{n-1} g_{ij} + \frac{1}{2} (\nabla_i \Omega_j + \nabla_j \Omega_i) = \underbrace{T_{ij} - \frac{g^{\alpha\beta} T_{\alpha\beta}}{n-1} g_{ij}}_{=:A_{ij}},$$

where $N^{\alpha}\partial_{\alpha}$ is the unit timelike normal to the initial data surface (compare (A.8)-(A.9), Appendix A). We have:

Proposition 4.2. Let $T_{\mu\nu}$ be divergence-free with respect to the time-independent metric

$$\mathbf{g} = -V^2 dt^2 + g$$

as a consequence of the matter field equations, with $\partial_t T_{\mu\nu} = T_{0i} = 0$. Set

$$(4.9) a := -T_{\alpha\beta}N^{\alpha}N^{\beta} - \frac{g^{\alpha\beta}T_{\alpha\beta}}{n-1}, A_{ij} := T_{ij} - \frac{g^{\alpha\beta}T_{\alpha\beta}}{n-1}g_{ij}.$$

Then

$$\beta \equiv 0.$$

Proof. Equation (4.6) can be rewritten as

$$(4.11) - \beta_{j} = \nabla_{i} \left(A^{i}{}_{j} - \frac{1}{2} (A^{k}{}_{k} + a) \delta_{j}^{i} \right) + V^{-1} \left(A_{ij} - a g_{ij} \right) \nabla V^{i}$$

$$= \nabla_{i} \left(T^{i}{}_{j} - \frac{1}{2} \left(\frac{2g^{\alpha\beta} T_{\alpha\beta}}{n-1} + A^{k}{}_{k} + a \right) \delta_{j}^{i} \right)$$

$$+ V^{-1} \left(T_{ij} - \left(\frac{g^{\alpha\beta} T_{\alpha\beta}}{n-1} - T_{\alpha\beta} N^{\alpha} N^{\beta} - \frac{g^{\alpha\beta} T_{\alpha\beta}}{n-1} \right) g_{ij} \right) \nabla V^{i}.$$

We have

$$\frac{2g^{\alpha\beta}T_{\alpha\beta}}{n-1} + A^{k}{}_{k} + a$$

$$= \frac{2g^{\alpha\beta}T_{\alpha\beta}}{n-1} + g^{ij}T_{ij} - \frac{n}{n-1}g^{\alpha\beta}T_{\alpha\beta} - T_{\alpha\beta}N^{\alpha}N^{\beta} - \frac{g^{\alpha\beta}T_{\alpha\beta}}{n-1} = 0.$$

The (n+1)-decomposition of the equation $\nabla^{\mu}T_{\mu\nu} = 0$, where ∇_{μ} is the space-time covariant derivative associated with \mathbf{g} , using the formulae for the Christoffel symbols in Appendix A gives

(4.12)
$$\nabla^{i}T_{ij} + VT_{\alpha\beta}N^{\alpha}N^{\beta}\nabla_{i}V + V^{-1}\nabla^{j}VT_{ij} = 0,$$

where ∇^i is the covariant derivative operator of g. Comparing with (4.11) gives the result.

5. The construction

We consider an asymptotically hyperbolic Einstein static metric $\mathring{\mathfrak{g}} = \mathring{V}^2 d\varphi^2 + \mathring{g}$ on $\mathbb{S}^1 \times M$. We apply Theorem 3.3 with s = -1, g — a Riemannian metric on M close to \mathring{g} in $C_0^{k+2,\alpha}(M,\mathcal{S}_2)$, and V — a function on M close to \mathring{V} in $C_{-1}^{k+2,\alpha}(M)$. It is convenient to choose some

(5.1)
$$\delta \in (0,1)$$
 when $n=3$ and $\delta=1$ if $n>3$.

We conclude that for any $\widehat{U} \in C^{k+2,\alpha}(\partial M)$, there exists a unique solution

$$U = U(\widehat{U}, V, g) \in C_0^{k+2, \alpha}(M)$$

to

$$\left\{ \begin{array}{l} \nabla^*(V^{-1}\nabla U)=0,\\ U-\widehat{U}\in C^{k+2,\alpha}_\delta(M)\,. \end{array} \right.$$

Moreover, the map $(\widehat{U},V,g)\mapsto U-\widehat{U}\in C^{k+2,\alpha}_\delta(M)$ is smooth.

We define a new map F, defined on the set of functions on the conformal boundary at infinity $\partial_{\infty} M$ times functions on M times symmetric two-tensor fields on M, mapping to functions on M times symmetric two-tensor fields on M, which to (\widehat{U}, V, g) associates

$$\left(\begin{array}{c} V(\nabla^*\nabla V + nV + \langle \Omega(V, g, \mathring{V}, \mathring{g}), dV \rangle) + \frac{n-2}{n-1} |dU|^2 \\ \operatorname{Ric}(g) + ng - V^{-1}\nabla_i \nabla_j V + \operatorname{div}^* \Omega(V, g, \mathring{V}, \mathring{g}) + V^{-2} (dU \otimes dU - \frac{1}{n-1} |dU|^2 g) \end{array} \right) .$$

PROPOSITION 5.1. Let $\mathring{\mathfrak{g}} = \mathring{V}^2 d\varphi^2 + \mathring{g}$ be an asymptotically hyperbolic static Einstein metric on $\mathbb{S}^1 \times M$, $k \in \mathbb{N}$, $\alpha \in (0,1)$. The map \mathcal{F} defined as

$$\begin{array}{ccc} C^{k+2,\alpha}(\partial M) \times C_1^{k+2,\alpha}(M) \times C_2^{k+2,\alpha}(M,\mathcal{S}_2) & \longrightarrow & C_0^{k,\alpha}(M) \times C_2^{k,\alpha}(M,\mathcal{S}_2) \\ (\widehat{U},W,h) & \longmapsto & F(\widehat{U},\mathring{V}+W,\mathring{g}+h) \end{array}$$

is smooth in a neighborhood of zero.

Proof. Let δ be as in (5.1). We have, by direct estimations,

$$V^{-2}(dU \otimes dU - \frac{1}{n-1}|dU|^2g) \in C^{k,\alpha}_{2+2\delta}(M,\mathcal{S}_2) \subset C^{k,\alpha}_2(M,\mathcal{S}_2)$$
.

The remaining arguments of the proof of [7, Proposition 5.2] apply with trivial modifications: The function $\mathring{V} \in C_{-1}^{k+2,\alpha}(M)$ is strictly positive, so the same is true for $\mathring{V}+W$ if W is sufficiently small in $C_1^{k+2,\alpha}(M) \subset C_{-1}^{k+2,\alpha}(M)$. Similarly, the symmetric two-tensor field $\mathring{g}+h \in C_0^{k+2,\alpha}(M,\mathcal{S}_2)$ is positive definite when h is small in $C_2^{k+2,\alpha}(M,\mathcal{S}_2) \subset C_0^{k+2,\alpha}(M,\mathcal{S}_2)$. The map $(\widehat{U},V,g)\mapsto U$ is smooth. The fact that the remaining terms in $F(\widehat{U},\mathring{V}+W,\mathring{g}+h)$ are in the space claimed, and that the map is smooth, follows from standard calculations (see [11, proof of Theorem 4.1] or [9, Appendix] for associated detailed calculations).

We are ready to formulate now:

THEOREM 5.2. Let dim $M = n \ge 3$ and let $\mathring{V}^2 d\varphi^2 + \mathring{g}$ be a non-degenerate asymptotically hyperbolic static Einstein metric on $\mathbb{S}^1 \times M$, $k \in \mathbb{N}$, $\alpha \in (0,1)$,

 $\delta \in (0,1)$ in n=3 and $\delta=1$ if n>3. For all \widehat{U} close to zero in $C^{k+2,\alpha}(\partial M)$ there exists a unique solution

$$(U, V, g) = (\widehat{U} + u, \mathring{V} + W, \mathring{g} + h)$$

to (4.2) with

$$(u, W, h) \in C_{\delta}^{k+2,\alpha}(M) \times C_{1}^{k+2,\alpha}(M) \times C_{2}^{k+2,\alpha}(M, \mathcal{S}_{2}),$$

close to zero, satisfying the gauge condition $\Omega = 0$. Moreover, the map $\widehat{U} \mapsto (u, W, h)$ is a smooth map of Banach spaces near zero.

Proof. As already pointed out, the function $U = U(\widehat{U}, V, g)$ exists and is unique when W and h are small. From Proposition 5.1 we know that the map \mathcal{F} is smooth. The linearisation of \mathcal{F} at zero is

$$D_{(W,h)}\mathcal{F}(0,0,0) = D_{(V,g)}F(0,\mathring{V},\mathring{g}) = (l,L).$$

From Corollary 3.1, with $\delta=2$, we obtain that $D_{(W,h)}\mathcal{F}(0,0,0)$ is an isomorphism. The implicit function theorem shows that the conclusion of Theorem 5.2 remains valid for the modified equation (4.3). Returning to Section 4.2, we see that $\Omega=\Omega(V,g,\mathring{V},\mathring{g})\in C_2^{k+1,\alpha}(M,T_1)$. Corollary 3.2 gives $\Omega=0$, and we have obtained a solution to (4.2).

PROOF OF THEOREM 1.1: Existence and uniqueness of a solution with

$$(5.2) V - \mathring{V} = O(\rho), U = \widehat{U} + O(\rho^{\delta}), g - \mathring{g} = O_{\mathring{g}}(\rho^{2}) = O_{\rho^{2}\mathring{g}}(1),$$

follows from Theorem 5.2. Here and elsewhere we write $u = O(\rho^{\sigma})$ for a tensor u if the coordinate components of u in local coordinates near the boundary are $O(\rho^{\sigma})$, and $u = O_{\mathring{g}}(\rho^{\sigma})$ if the norm $|u|_{\mathring{g}}$ of u with respect to the metric \mathring{g} is $O(\rho^{\sigma})$. Standard arguments show that all the fields V, U and g are polyhomogeneous (cf. e.g. [8], compare [7, Section 7]).

To justify (1.7), we plug-in a polyhomogeneous asymptotics as in (5.2) in the equations. Since the trace-free part of the Ricci tensor of $\mathbf{g} = -V^2 dt^2 + g$ decays in $\mathring{\mathfrak{g}}$ -norm as ρ^4 near $\rho = 0$, the metric $\mathbf{g} = -V^2 dt^2 + g$ is vacuum up to this order, which implies that the usual Fefferman-Graham expansion holds this metric up to terms $O_{\mathring{\mathfrak{g}}}(\rho^4 \ln \rho)$. This leads to the following form of the metric near the conformal boundary

(5.3)
$$\mathring{g} = \rho^{-2} (d\rho^2 + \mathring{h}) , \quad \mathring{h} = \widecheck{h} + O_{\widecheck{h}}(\rho^2) , \quad \mathring{V} = \widecheck{V} \rho^{-1} + O(\rho) ,$$

where h is a family of Riemannian metrics on the boundary depending upon ρ , with

$$g = \mathring{g} + O_{\mathring{g}}(\rho^2) , \quad V = \mathring{V} + O(\rho) .$$

The equation $\nabla_i(V^{-1}\nabla^i U)=0$ in local coordinates (ρ,x^A) as in (5.3) takes the form

$$\check{V}^{-1}\sqrt{\det\check{h}}\,\partial_{\rho}\left[\rho^{3-n}(1+O(\rho^{2}))\partial_{\rho}U\right]
= -\rho^{3-n}\partial_{A}\left[\left(\check{V}^{-1}\sqrt{\det\check{h}}+O(\rho^{2})\right)\left(\check{h}^{AB}+O^{AB}(\rho^{2})\right)\partial_{B}U\right]
+\partial_{\rho}\left(\rho^{5-n}O^{A}(1)\partial_{A}U\right) +\partial_{A}\left(\rho^{5-n}O^{A}(1)\partial_{\rho}U\right).$$

Let U a polyhomogenous solution with $U = \widehat{U} + O(\rho^{\delta})$. When n = 3, we can see that no logarithmic term $O(\rho \ln \rho)$ is needed in U so that $U = \widehat{U} + O(\rho)$. When n = 4, we find

(5.4)
$$U = \widehat{U} \underbrace{-\frac{1}{2} \breve{V} \breve{\nabla}_A (\breve{V}^{-1} \breve{\nabla}^A \widehat{U})}_{=:U_{ln}} \rho^2 \ln \rho + O(\rho^2).$$

(In dimensions $n \geq 5$ on expects in general a logarithmic term $O(\rho^{n-2} \ln \rho)$ in an asymptotic expansion of U.)

Remark 5.3. The equality

$$2\int_{\partial M} \breve{V}^{-1}\widehat{U}U_{\ln} = \int_{\partial M} \breve{V}^{-1} |\breve{\nabla}\widehat{U}|^2,$$

proves that $U_{\ln} = 0$ if and only if \widehat{U} is constant. When \widehat{U} is constant the function $U := \widehat{U}$ solves the equations and satisfies the right-boundary values, so the associated solution is vacuum.

Appendix A. Static Einstein-Maxwell equations in dimensions $n+1 \geq 4$

Consider a Riemannian manifold (M, g), let us denote by ∇ the Levi-Civita derivative operator associated with g. Let $V: M \to \mathbb{R}$, and set

$$(\mathcal{M} = \mathbb{R} \times M, \widetilde{g} = \varepsilon V^2 dt^2 + g), \quad \varepsilon = \pm 1,$$

and $(x^{\mu}) = (x^0 = t, x^i = (x^1, ..., x^n))$. We have

(A.1)
$$\widetilde{\Gamma}_{00}^0 = \widetilde{\Gamma}_{ij}^0 = \widetilde{\Gamma}_{i0}^k = 0$$
, $\widetilde{\Gamma}_{i0}^0 = V^{-1}\partial_i V$, $\widetilde{\Gamma}_{00}^k = -\varepsilon V \nabla^k V$, $\widetilde{\Gamma}_{ij}^k = \Gamma_{ij}^k$,

$$(\mathrm{A.2}) \hspace{0.5cm} \widetilde{R}^l{}_{ijk} = R^l{}_{ijk}, \hspace{0.2cm} \widetilde{R}^l{}_{0j0} = -\varepsilon V \nabla_j \nabla^l V, \hspace{0.2cm} \widetilde{R}^0{}_{ij0} = V^{-1} \nabla_j \nabla_i V \,,$$

(A.3)
$$\widetilde{R}^{0}{}_{ijk} = \widetilde{R}^{l}{}_{ij0} = \widetilde{R}^{l}{}_{0jk} = \widetilde{R}^{0}{}_{0jk} = \widetilde{R}^{0}{}_{0j0} = 0,$$

(A.4)
$$\widetilde{R}_{ik} = R_{ik} - V^{-1} \nabla_k \nabla_i V$$
, $\widetilde{R}_{0k} = 0$, $\widetilde{R}_{00} = -\varepsilon V \nabla^i \nabla_i V$,

$$\widetilde{R} = R - 2V^{-1}\nabla^i \nabla_i V .$$

Consider the (n + 1)-dimensional Einstein equations

(A.6)
$$\tilde{R}_{\alpha\beta} - \frac{1}{2}\tilde{R}\tilde{g}_{\alpha\beta} + \Lambda\tilde{g}_{\alpha\beta} = T_{\alpha\beta}.$$

Equations (A.6) with $\tilde{g} = -V^2 dt^2 + g$ lead to

(A.7)
$$\widetilde{R}_{\alpha\beta} = \frac{2\Lambda - \operatorname{Tr}_{\widetilde{g}} T}{n-1} \widetilde{g}_{\alpha\beta} + T_{\alpha\beta} ,$$

(A.8)
$$R_{ij} = V^{-1} \nabla_i \nabla_j V + \frac{2\Lambda}{n-1} g_{ij} + T_{ij} - \frac{\text{Tr}_{\tilde{g}} T}{n-1} g_{ij},$$

(A.9)
$$V\nabla^{i}\nabla_{i}V = V^{2}\left(T_{\alpha\beta}N^{\alpha}N^{\beta} + \frac{\operatorname{Tr}_{\tilde{g}}T - 2\Lambda}{n-1}\right),$$

where $N^{\alpha}\partial_{\alpha}$ is the unit timelike normal to the level sets of t.

For a static electric field F = d(Udt), $\partial_t U = 0$, and $T_{\mu\nu}$ as in (1.1) we find

$$(A.10) |F|^2 = -2V^{-2}|dU|^2,$$

(A.11)
$$\tilde{g}^{\mu\nu}T_{\mu\nu} \equiv \operatorname{Tr}_{\tilde{g}}T = \frac{(3-n)}{4}|F|^2 = -\frac{(3-n)}{2}V^{-2}|dU|^2$$
,

(A.12)
$$T_{ij} = -V^{-2}\nabla_i U \nabla_j U + \frac{1}{2}V^{-2}|dU|^2 g_{ij},$$

(A.13)
$$g^{ij}T_{ij} = \frac{(n-2)}{2}V^{-2}|dU|^2$$

(A.14)
$$T_{\widehat{00}} := T_{\mu\nu} N^{\mu} N^{\nu} = \frac{1}{2} V^{-2} |dU|^2.$$

Choosing Λ as in (4.1), Equation (A.9) gives

(A.15)
$$V\Delta V = \frac{n-2}{(n-1)}|dU|^2 - \frac{2\Lambda V^2}{n-1} = \frac{n-2}{(n-1)}|dU|^2 + nV^2$$
.

When $\widetilde{g} = \varepsilon V^2 dt^2 + g$ is static and

(A.16)
$$T = T_{00}(dx^{0})^{2} + T_{ij}dx^{i}dx^{j}, \quad \partial_{0}T_{00} = \partial_{0}T_{ij} = 0,$$

then

(A.17)
$$\tilde{\nabla}^{\alpha} T_{\alpha\beta} dx^{\beta} = \left(\nabla^{i} T_{ij} + V^{-1} \nabla^{i} V T_{ij} - \varepsilon V^{-3} \nabla_{j} V T_{00}\right) dx^{j}.$$

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