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Erwann Delay

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# CONFORMALLY COVARIANT PARAMETERIZATION FOR RELATIVISTIC INITIAL DATA 

ERWANN DELAY


#### Abstract

We modify the Lichnerowicz-York method in order to obtain conformally covariant systems. This type of parametrization is certainly more natural for non constant mean curvature initial data.


Keywords : Conformal riemannian geometry, non linear elliptic PDE system, vectorial laplacian, general relativity, constraints equations.

2010 MSC : 53C21, 53A45, 53A30, 58J05, 35J61.

## 1. Introduction

On a smooth manifold $M$ of dimension $n$, for a riemannian metric $g$, we denote by $R_{g}$ its scalar curvature and $\nabla$ its Levi-Civita connexion. When $h$ is a field of symmetric covariants two tensors, we define its divergence, as the 1 -form given by

$$
\left(\operatorname{div}_{g} h\right)_{i}=-\nabla^{k} h_{k i} .
$$

The vacuum initial data for the relativistic Einstein equations are given by a riemannian metric $\widehat{g}$ and a symmetric two tensor field $\widehat{K}$, verifying the constraints equations

$$
(C)\left\{\begin{array}{l}
R_{\widehat{g}}-|\widehat{K}|_{\widehat{g}}^{2}+\left(\operatorname{Tr}_{\widehat{g}} \widehat{K}\right)^{2}=0 \\
\operatorname{div}_{\widehat{g}} \widehat{K}+d\left(\operatorname{Tr}_{\widehat{g}} \widehat{K}\right)=0
\end{array}\right.
$$

This system is highly under-determined because it contains $(n+1)$ equations for $n(n+1)$ unknowns. It is natural to fix some of the unknowns, and to look for the $(n+1)$ remaining ones.

The usual conformal parameterization, where appear the 1944 Lichnerowicz equation [2], together with the 1973 York decomposition [7], was very studied by a lot of authors, on compact or non compact manifolds (asymtotic to some models : euclidean, hyperbolic, cylindrical,...).

The list of studies on the subject, being too substantial to be given here, we just mention a recent paper [5] and its references for a fleeting glimpse.

We simply recall that after the approaches realized for constant mean curvature $\tau$, like [1] for instance, several attempts where given in order to treat some cases where this last one is changing.

The method start with a metric $g$, together with a trace free and divergence free symmetric two tensor $\sigma$ (a TT-tensor), and a function $\tau$. One look for the solutions to the constraint equations of the form

$$
\begin{equation*}
\widehat{g}=\phi^{N-2} g, \quad \widehat{K}=\frac{\tau}{n} \widehat{g}+\phi^{-2}\left(\sigma+\stackrel{\circ}{\mathcal{L}}_{g} W\right), \tag{P}
\end{equation*}
$$

where $N=\frac{2 n}{n-2}$, and the unknowns are a function $\phi>0$ and a field of one forms $W$ and where

$$
\left(\stackrel{\circ}{\mathcal{L}}_{g} W\right)_{i j}=\nabla_{i} W_{j}+\nabla_{j} W_{i}-\frac{2}{n} \nabla^{k} W_{k} g_{i j} .
$$

If we denote

$$
w=\left|\sigma+\stackrel{\circ}{\mathcal{L}}_{g} W\right|_{g}
$$

we have to solve the coupled system

$$
(S)\left\{\begin{array}{l}
P_{g, w} \phi:=\frac{4(n-1)}{n-2} \nabla^{*} \nabla \phi+R_{g} \phi-w^{2} \phi^{-N-1}=\frac{1-n}{n} \tau^{2} \phi^{N-1}  \tag{L}\\
\operatorname{div}_{g} \mathcal{L}_{g} W=\frac{1-n}{n} \phi^{N} d \tau
\end{array}\right.
$$

The Lichnerowicz equation $(L)$ has a covariantly conformal property (see section 8.2 for a precise definition). Indeed, if $\phi$ is a solution of $(L)$, and $\varphi$ is any positive function, we may write

$$
\tilde{g}=\varphi^{N-2} g, \quad \tilde{w}=\varphi^{-N} w, \quad \tilde{\phi}=\varphi^{-1} \phi
$$

then

$$
P_{\tilde{g}, \tilde{w}} \tilde{\phi}=\varphi^{1-N} P_{g, w} \phi=\frac{1-n}{n} \tau^{2} \tilde{\phi}^{N-1} .
$$

However, the vectorial equation $(V)$ does not possess this property. Moreover, the conformal transformation of $w$ used here on $(L)$ does not correspond to a natural transformation of $\sigma$ and $W$.

Let us note that some of the operators appearing in $(V)$ are conformally covariants :

$$
\begin{equation*}
\operatorname{div}_{\tilde{g}} h=\varphi^{-N} \operatorname{div}_{g}\left(\varphi^{2} h\right), \quad \dot{\mathcal{L}}_{\tilde{g}} X=\varphi^{N-2} \dot{\mathcal{L}}_{g}\left(\varphi^{2-N} X\right) \tag{C}
\end{equation*}
$$

although the vector Laplacian div $\circ \mathcal{L}$ does not be.
Finally, we would point out the York decomposition [7] valid for instance if $M$ is compact and $g$ has no conformal Killing fields (ie. ker $\dot{\mathcal{L}}_{g}$ is trivial). Any field of covariant symmetric trace free two tensor $h$ split in a unique way as

$$
\begin{equation*}
h=\sigma+\grave{\mathcal{L}}_{g} W, \tag{Y}
\end{equation*}
$$

where $\sigma$ is a TT-tensor and $W$ a field of 1-forms.

We propose in the section 2 a parameterization ensuing the York decomposition relative to $\widehat{g}$ and not to $g$. This parameterization give rise to a conformally covariant system.

This last one leds to the emergence of a vectorial laplacian, self adjoint for a weighted mesure, it will be studied in section 3 .

In the section 4, we test some other parameterizations and compare them.
In the section 5, a linear version of the obtained system is computed. This last one suggest to study another system, it is given in section 6 and leads to a final parameterization who is certainly the more natural.

Finally, in section 7, we emphasise some comments related to the evident continuation to this work.

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## 2. A first conformally covariant parameterization

Let us come back to $(C)$ but using the York decomposition relative to $\widehat{g}$,

$$
\widehat{K}-\frac{\tau}{n} \widehat{g}=\widehat{\sigma}+\dot{\mathcal{L}}_{\widehat{g}} \widehat{W}
$$

It follows that $(C)$ is equivalent to

$$
\left(C^{\prime}\right)\left\{\begin{array}{l}
R_{\widehat{g}}-\left|\widehat{\sigma}+\dot{\mathcal{L}}_{\widehat{g}} \widehat{W}\right|_{\widehat{g}}^{2}=\frac{1-n}{n} \tau^{2} \\
\operatorname{div}_{\widehat{g}} \grave{L}_{\widehat{g}} \widehat{W}=\frac{1-n}{n} d \tau \\
\operatorname{div}_{\widehat{g}} \widehat{\sigma}^{2}=0
\end{array}\right.
$$

If we are looking for a solution in a conformal class $\widehat{g}=\phi^{N-2} g$, from $(\mathcal{C})$, it is natural to introduce $\widehat{\sigma}=\phi^{-2} \sigma$, where $\sigma$ is a TT-tensor. The third equation is then automatically satisfied. But again using $(\mathcal{C})$, if we translate the second equation in term of $g$, it came spontaneously $\widehat{W}:=\phi^{N-2} W$.

Thus, already with the same fixed $g, \sigma, \tau$, we can parametrize the solutions of the constraint ( $C$ ) by

$$
\left(P^{\prime}\right)\left\{\begin{array}{l}
\widehat{g}=\phi^{N-2} g, \\
\widehat{K}=\frac{\tau}{n} \widehat{g}+\phi^{-2}\left(\sigma+\phi^{N} \dot{\mathcal{L}}_{g} W\right)
\end{array}\right.
$$

With this parameterization in $(C)$, if we define

$$
\omega=\omega(\sigma, \phi, W, g):=\left|\sigma+\phi^{N} \stackrel{\circ}{\mathcal{L}}_{g} W\right|_{g}
$$

we obtain the new system

$$
\left(S^{\prime}\right) \begin{cases}P_{g, \omega} \phi=\frac{1-n}{n} \tau^{2} \phi^{N-1} & \left(L^{\prime}\right) \\ \Delta_{g, \phi} W:=\phi^{-N} \operatorname{div}_{g}\left(\phi^{N} \dot{\mathcal{L}}_{g} W\right)=\frac{1-n}{n} d \tau & \left(V^{\prime}\right)\end{cases}
$$

We now go through the conformal changes:

$$
\tilde{g}=\varphi^{N-2} g, \quad \tilde{\phi}=\varphi^{-1} \phi, \quad \tilde{\sigma}=\varphi^{-2} \sigma, \quad \tilde{W}=\varphi^{N-2} W .
$$

Note that by $(\mathcal{C})$, the tensor $\tilde{\sigma}$ is still TT for $\tilde{g}$. This time round

$$
\tilde{\omega}:=\omega(\tilde{\sigma}, \tilde{\phi}, \tilde{W}, \tilde{g})=\varphi^{-N} \omega
$$

so the scalar equation $\left(L^{\prime}\right)$ behave like above. For the new vectorial equation $\left(V^{\prime}\right)$, because from $(\mathcal{C})$,

$$
\Delta_{\tilde{g}, \tilde{\phi}} \tilde{W}=\Delta_{g, \phi} W,
$$

it became conformally covariant.

## Remarks :

- When $\varphi=\phi$ we fall on $\Delta_{g, \phi} W=\Delta_{\widehat{g}, 1} \widehat{W}$.
- As $\omega$ depend on $\phi$, the following version of $\left(L^{\prime}\right)$ is more explicit :

$$
\begin{align*}
\frac{4(n-1)}{n-2} \nabla^{*} \nabla \phi+R_{g} \phi-|\sigma|^{2} \phi^{-N-1}-2\left\langle\sigma, \grave{\mathcal{L}}_{g} W\right\rangle \phi^{-1} & -\left|\AA_{g} W\right|_{g}^{2} \phi^{N-1} \\
& =\frac{1-n}{n} \tau^{2} \phi^{N-1}
\end{align*}
$$

- Let us consider the operator given by

$$
\mathcal{P}_{g}\left(\begin{array}{l}
\phi \\
W \\
\sigma
\end{array}\right):=\left(\begin{array}{l}
\phi^{1-N} P_{g, \omega} \phi \\
\Delta_{g, \phi} W \\
\phi^{-N} \operatorname{div}_{g} \sigma
\end{array}\right)
$$

in such a way that $\mathcal{P}_{g}$ is conformally covariant :

$$
\mathcal{P}_{\tilde{g}}\left(\begin{array}{l}
\tilde{\phi} \\
\tilde{W} \\
\tilde{\sigma}
\end{array}\right)=\mathcal{P}_{g}\left(\begin{array}{l}
\phi \\
W \\
\sigma
\end{array}\right) .
$$

The system $\left(S^{\prime}\right)$ (modulo adding the third equation) is simply written

$$
\mathcal{P}_{g}\left(\begin{array}{l}
\phi \\
W \\
\sigma
\end{array}\right)=\frac{1-n}{n}\left(\begin{array}{l}
\tau^{2} \\
d \tau \\
0
\end{array}\right)
$$

- There was been some others tentative to modify the LichnerowiczYork method, like the "Conformal Thin-Sandwich" (see for instance [5] for a comparison, see also [6]). In particular, there already exist some parameterizations where

$$
\widehat{K}=\frac{\tau}{n} \widehat{g}+\phi^{-2}\left(\sigma+f \dot{\mathcal{L}}_{g} W\right)
$$

but the function $f$ seems always fixed at first, and not a function of $\phi$, but $f=\phi^{N}$ is the simplest one to make the system conformally covariant (see sections 4 and 6 for some others possibilities).

- More generally, for any covariantly conform differential linear operator of order $k$, we could interpose a function between itself and its formal adjoint, in order to produce an operator of order $2 k$, covariantly conform, positive and self adjoint for a weighted measure.


## 3. The vectorial equation

We consider the vectorial laplacian, of Witten type, obtained previously :

$$
\Delta_{g, \phi} W=\phi^{-N} \operatorname{div}_{g} \phi^{N} \stackrel{\circ}{\mathcal{L}}_{g} W=\operatorname{div}_{g} \check{\mathcal{L}}_{g} W-N \check{\mathcal{L}}_{g} W(\nabla \ln \phi, .)
$$

We choose to work here on a compact manifold. Because $2 \operatorname{div}_{g}$ is the formal $L^{2}\left(d \mu_{g}\right)$ adjoint of $\mathcal{L}_{g}$, we have

$$
\int_{M}\left\langle\Delta_{g, \phi} W, V\right\rangle_{g} \phi^{N} d \mu_{g}=\frac{1}{2} \int_{M}\left\langle\dot{\mathcal{L}}_{g} W, \dot{\mathcal{L}}_{g} V\right\rangle_{g} \phi^{N} d \mu_{g}
$$

This Laplacian is then $L^{2}\left(\phi^{N} d \mu_{g}\right)$ self adjoint and its kernel is reduced to conformal killing 1 -forms.

We want to solve (with for simplification $g, \phi, \tau$ smooth, we could also choose $\phi \in L^{\infty}$ ),

$$
\Delta_{g, \phi} W=\frac{1-n}{n} d \tau
$$

By the Fredholm alternative, a necessary and sufficient condition for existence is orthogonality to the kernel:

$$
\int_{M}\langle X, d \tau\rangle_{g} \phi^{N} d \mu_{g}=0
$$

for all $X$ in ker $\stackrel{\circ}{\mathcal{L}}_{g}$. The uniqueness occurring up to the addition of an element of ker $\dot{\mathcal{L}}_{g}$. Note that if $\tilde{X}=\varphi^{N-2} X$,

$$
\langle\tilde{X}, Y\rangle_{\tilde{g}} \tilde{\phi}^{N} d \mu_{\tilde{g}}=\langle X, Y\rangle_{g} \phi^{N} d \mu_{g}
$$

then because of $(\mathcal{C})$, the condition $(\perp)$ is conformally covariant. It can be written

$$
\int_{M} \tau d_{g}^{*}\left(\phi^{N} X\right) d \mu_{g}=0
$$

Of course, if $g$ does not possess some conformal Killing, the equation $\left(V^{\prime}\right)$ always has a unique solution whatever the (positive) function $\phi$ is.

If $\mathcal{K}=\operatorname{ker} \stackrel{\mathcal{L}}{ }$ is not trivial, we may define $\Pi_{g, \phi}$ the orthogonal projection on $\mathcal{K}$ for the weighted scalar product :

$$
(X, Y)_{g, \phi}=\int_{M}\langle X, Y\rangle_{g} \phi^{N} d \mu_{g}
$$

We can then solve

$$
\Delta_{g, \phi} W=\frac{1-n}{n}\left(I d-\Pi_{g, \phi}\right) d \tau, \quad\left(V_{\Pi}^{\prime}\right)
$$

$W$ being unique if it is chosen orthogonal to $\mathcal{K}$ (for the weighted scalar product).

Remark : By analogy with the Witten laplacian, we could consider the similar laplacian $\phi^{-\frac{N}{2}} \operatorname{div}\left(\phi^{\frac{N}{2}} \phi^{\frac{N}{2}} \dot{\mathcal{L}} \phi^{-\frac{N}{2}}\right)$.

## 4. Some others parameterizations and matching

Let us consider another conformal metric $\tilde{g}=\varphi^{N-2} g$. The York decomposition $(Y)$, related to $\tilde{g}$, of the tensor

$$
\phi^{2} \varphi^{-2}\left(\widehat{K}-\frac{\tau}{n} \widehat{g}\right),
$$

culminated to the parameterization

$$
\left(P_{\varphi}\right)\left\{\begin{array}{l}
\widehat{g}=\phi^{N-2} g \\
\widehat{K}=\frac{\tau}{n} \widehat{g}+\phi^{-2}\left(\sigma+\varphi^{N} \dot{\mathcal{L}}_{g} W\right)
\end{array}\right.
$$

With this parameterization in $(C)$, if we denote by

$$
\omega_{\varphi}=\omega(\sigma, \varphi, W, g):=\left|\sigma+\varphi^{N} \dot{\mathcal{L}}_{g} W\right|_{g},
$$

we obtain the new system

$$
\left(S_{\varphi}\right) \begin{cases}P_{g, \omega_{\varphi}} \phi=\frac{1-n}{n} \tau^{2} \phi^{N-1} & \left(L_{\varphi}\right) \\ \phi^{-N} \operatorname{div}_{g}\left(\varphi^{N} \mathcal{L}_{g} W\right)=\frac{1-n}{n} d \tau & \left(V_{\varphi}\right)\end{cases}
$$

If $g$ has no conformal killing, by (Y), for all $W$ and all function $\varphi$, there exist a unique field of 1-forms $V$ and a TT-tensor $\sigma^{\prime}$ such that

$$
\sigma^{\prime}+\grave{\mathcal{L}}_{g} V=\varphi^{N} \dot{\mathcal{L}}_{g} W
$$

It follows that the solutions of any system $\left(S_{\varphi}\right)$ match, but for different $\sigma$.

REmark: We may take $\varphi$ depending of $\phi$ and eventually of some other parameters in the (then abusively denoted) system $\left(P_{\varphi}\right)$. For instance $\varphi^{N}=\phi^{N} F^{2}\left(|\mathcal{L} W|_{g}\right)$, for a function $F$, will give again a conformally covariant system of order of derivation 2. The parameterization $\varphi^{N}=$ $|\tau| \phi^{N}$ seems also produce an interesting system.

## 5. A linear version

In order to a better understanding of some future studies of $\left(S^{\prime}\right)$, we will linearise here the operator $\mathcal{P}_{g}$ introduced in section 2 . We denote by $(\psi, V, h)$ the variations of $(\phi, W, \sigma), v$ the variation of $\tau$, we keep here the metric $g$ fixed. Because of the conformally covariant properties
of $\mathcal{P}_{g}$, the computation of the linearisation can be done at $\phi=1$. We then find
$D \mathcal{P}_{g}^{(1, W, \sigma)}\left(\begin{array}{c}\psi \\ V \\ h\end{array}\right)=\left(\begin{array}{ccc}P_{g, \sigma, W} & -2\langle\stackrel{\circ}{K}, \stackrel{\circ}{\mathcal{L}} .\rangle, & -2\langle\stackrel{\circ}{K}, .\rangle \\ -N \dot{\mathcal{L}}_{g} W\left(\nabla_{g} ., .\right) & \operatorname{div}_{g} \mathcal{L}_{g} & 0 \\ 0 & 0 & \operatorname{div}_{g}\end{array}\right)\left(\begin{array}{l}\psi \\ V \\ h\end{array}\right)$
where

$$
\stackrel{\circ}{K}=\sigma+\stackrel{\circ}{\mathcal{L}}_{g} W
$$

and

$$
\begin{aligned}
& P_{g, \sigma, W}=\frac{4}{n-2}\left((n-1) \nabla^{*} \nabla-R_{g}+n|\sigma|^{2}+n\left\langle\sigma, \mathcal{L}_{g} W\right\rangle\right) \\
& =\frac{4}{n-2}\left((n-1) \nabla^{*} \nabla-R_{g}+\frac{n}{2}\left(|\sigma|^{2}+|\stackrel{\circ}{K}|^{2}-\left|\grave{\mathcal{L}}_{g} W\right|^{2}\right)\right) .
\end{aligned}
$$

This last operator, evaluated at a solution of ( $S^{\prime}$ ), can be written using the Yamabe laplacian, because

$$
R_{g}=\left|\AA{ }^{\circ}\right|^{2}+\frac{1-n}{n} \tau^{2} .
$$

The linear version of the system becomes

$$
D \mathcal{P}_{g}^{(1, W, \sigma)}\left(\begin{array}{l}
\psi \\
V \\
h
\end{array}\right)=\frac{1-n}{n}\left(\begin{array}{l}
2 \tau v \\
d v \\
0
\end{array}\right)
$$

If $\sigma$ is fixed, its impose $h=0$, if not, the global form of the system suggest to look about some others possibilities.

## 6. An other conformally covariant parameterization

In the parameterization of the section 2 , we choose a fixed $T T$ tenseur $\sigma$ and defined $\widehat{\sigma}=\phi^{-2} \sigma$ in order to verify immediately the last equation of the system $\left(C^{\prime}\right)$. Without this particular choice, $\left(C^{\prime}\right)$ has $2 n+1$ equations. Rather than that, we can fix a trace free tensor $\stackrel{\circ}{\sigma}$ an look for the unique TT-tensor $\widehat{\sigma}$ for $\widehat{g}$, such that

$$
\phi^{-2} \stackrel{\circ}{\sigma}=\widehat{\sigma}-\dot{\mathcal{L}}_{\widehat{g}} \widehat{Y} .
$$

It is then convenient to define

$$
\widehat{\sigma}=\phi^{-2}\left(\stackrel{\circ}{\sigma}+\phi^{N} \dot{\mathcal{L}}_{g} Y\right), \quad \varpi=\left|\stackrel{\circ}{\sigma}+\phi^{N} \dot{\mathcal{L}}_{g} Y+\phi^{N} \dot{\mathcal{L}}_{g} W\right|
$$

It result the conformally covariant system

$$
\left(S^{\prime \prime}\right) \begin{cases}\phi^{1-N} P_{g, \varpi} \phi=\frac{1-n}{n} \tau^{2} & \left(L^{\prime \prime}\right) \\ \Delta_{g, \phi} W=\frac{1-n}{n} d \tau & \left(V_{1}^{\prime \prime}\right) \\ \Delta_{g, \phi} Y=-\phi^{-N} \operatorname{div}_{g} \stackrel{\circ}{\sigma} . & \left(V_{2}^{\prime \prime}\right)\end{cases}
$$

The matching linear operator has the form :

$$
\left(\begin{array}{c}
\phi^{1-N} P_{g, \infty} \phi \\
\Delta_{g, \phi} \\
\Delta_{g, \phi}
\end{array}\right)^{\prime}=\left(\begin{array}{ccc}
P_{g, \delta, W, Y} & -2\langle\stackrel{\circ}{K}, \dot{\mathcal{L}} .\rangle, & -2\langle\stackrel{\circ}{K}, \stackrel{\circ}{\mathcal{L}} .\rangle \\
-N \dot{\mathcal{L}}_{g} W\left(\nabla_{g} ., .\right) & \Delta_{g, 1} & 0 \\
-N \mathcal{L}_{g} Y\left(\nabla_{g}, .\right) & 0 & \Delta_{g, 1}
\end{array}\right)
$$

where

$$
\stackrel{\circ}{K}=\stackrel{\circ}{\sigma}+\dot{\mathcal{L}}_{g} Y+\stackrel{\circ}{\mathcal{L}}_{g} W,
$$

and

$$
\begin{aligned}
& P_{g, \delta, W, Y, Y}=\frac{4}{n-2}\left((n-1) \nabla^{*} \nabla-R_{g}+n|\circ|^{2}+n\left\langle\stackrel{\circ}{\sigma}, \stackrel{\circ}{\mathcal{L}}_{g}(W+Y)\right\rangle\right) \\
& =\frac{4}{n-2}\left((n-1) \nabla^{*} \nabla-R_{g}+\frac{n}{2}\left(|\dot{\sigma}|^{2}+|\stackrel{\circ}{K}|^{2}-\left|\dot{\mathcal{L}}_{g}(W+Y)\right|^{2}\right)\right) .
\end{aligned}
$$

This operator evaluated at a solution of $\left(S^{\prime \prime}\right)$, can agian be written with the Yamabe laplacian, because then

$$
R_{g}=|\stackrel{\circ}{K}|^{2}+\frac{1-n}{n} \tau^{2}
$$

A retrospection about this last system shows that only $X=Y+W$ is important and the natural system to solve seems to be

$$
\left(S^{\prime \prime \prime}\right) \begin{cases}\phi^{1-N} P_{g, w} \phi=\frac{1-n}{n} \tau^{2} & \left(L^{\prime \prime \prime}\right) \\ \Delta_{g, \phi} X=\frac{1-n}{n} d \tau-\phi^{-N} \operatorname{div}_{g} \sigma & \left(V^{\prime \prime \prime}\right)\end{cases}
$$

where we recall that the function $\tau$, and the trace free symmetric two tensor $\stackrel{\circ}{\sigma}$ are given. The parameterization for the solutions of $(C)$ being then

$$
\widehat{g}=\phi^{N-2} g, \quad \widehat{K}=\phi^{-2}\left(\stackrel{\circ}{\sigma}+\phi^{N} \dot{\mathcal{L}}_{g} X\right) \quad\left(P^{\prime \prime \prime}\right)
$$

Remark: We come back to the system ( $S^{\prime}$ ) if we choose a divergence free $\stackrel{\circ}{\sigma}$.

## 7. COMMENTS AND PROSPECTS

We give here some comments together with the first fruits of a future study of conformally covariants systems, starting with the compact manifolds.

- Other York decompositions : Conformally covariant or not, some other choices of $\varphi=\varphi(\phi, W, \sigma, \tau, t, f, \ldots)$ in $\left(S_{\varphi}\right)$ may be judicious.
- Contraints with right hand side : The parameterization works for some other stress energy tensors like for a scalar field for instance.
- Matching of parameterizations: Because of the matching beetween the differents parameterizations, the solutions of $(S)$ already existing produce some solutions of $\left(S^{\prime}\right)$ for example, even if it means to change the parameters. If we consider the set of solutions of $(C)$ as a manifold, it is probable that the conformal method give a local chart, but a
conformally covariant method produce a more global chart, and allows a larger choice of $(\tau, \sigma)$ (or $(\tau, \circ \circ)$ for $\left.\left(S^{\prime \prime \prime}\right)\right)$.
- Variational study : The systems we obtains are not triangular like for the clasical conformal method. However, a variational study will be particularly adjusted.
- Fixed point : As for a lot of studies of $(S)$, a classical method to solve a system like $\left(S^{\prime}\right)$ is to consider a map $T: E \rightarrow E$, for an appropriate space $E$, defined like this. If there is no conformal killing, for $\psi$ in $E$, we consider the solution $W$ of ( $\mathrm{V}^{\prime}$ ) with $\phi$ replaced by $\psi$. We then define $\omega:=\omega(\sigma, \psi, W, g)$ and we solve ( $L^{\prime}$ ) (see for instance [4]), The solution define $T(\psi):=\phi$. We the have to look for a fixed point $\phi>0$ of $T$. If necessary, we could fit some $\phi$ together with some $\psi$ in the choice of $\omega$ (and/or in $\left(L^{\prime}\right)$ ) and solve another scalar equation, similar to $\left(L^{\prime}\right)$ on $\phi$, for example linear relatively to $\phi$. If there exist some conformal killing field, we can in the process, replace the solving of $\mathrm{d}\left(V^{\prime}\right)$ by the one of $\left(V_{\Pi}^{\prime}\right)$, if under appropriate conditions, the projection disappear at the limit.
- The limit equation : In [3] a (family of ) limit equation(s) is given for $(S)$. It has the upsetting property to guaranty the resolvability of $(S)$, if itself has zero as unique solution. We have to look if this limit equation measure the asymmetry of the old parameterization or if a similar equation exist for the system $\left(S^{\prime \prime \prime}\right)$.


## 8. Appendice

### 8.1. Vector laplacian.

$$
\begin{aligned}
& \operatorname{div}_{g} \stackrel{\mathcal{L}}{g}=\nabla_{g}^{*} \nabla_{g}-\operatorname{Ric}_{g}+\frac{n-2}{2} d d_{g}^{*} \\
&=\Delta_{\text {Hodge }-2 \operatorname{Ric}_{g}+\frac{n-2}{2} d d_{g}^{*}} \\
&=d_{g}^{*} d+\frac{n}{2} d d_{g}^{*}-2 \operatorname{Ric}_{g}
\end{aligned}
$$

8.2. Conformal covariance. Let us consider tree products of tensor bundles over $M$,

$$
E=E_{1} \times \ldots \times E_{k}, \quad F=F_{1} \times \ldots \times F_{l}, \quad G=G_{1} \times \ldots \times G_{m},
$$

and a differential operator acting on the sections :

$$
P_{g}: \Gamma(E) \longrightarrow \Gamma(F),
$$

with coefficients determined by $g=\left(g_{1}, \ldots, g_{m}\right) \in G$. We will said that $P_{g}$ is conformally covariant if there exist $a=\left(a_{1}, . ., a_{k}\right) \in \mathbb{R}^{k}$, $b=\left(b_{1}, . ., b_{l}\right) \in \mathbb{R}^{l}$ and $c=\left(c_{1}, . ., c_{m}\right) \in \mathbb{R}^{m}$ such that for all smooth section $e$ of $E$, and any smooth function $\varphi$ on $M$, we have

$$
\varphi^{b} \odot P_{\varphi^{c} \odot g}\left(\varphi^{a} \odot e\right)=P_{g}(e),
$$

where we have defined for instance

$$
\varphi^{a} \odot e=\left(\varphi^{a_{1}} e_{1}, \ldots, \varphi^{a_{k}} e_{k}\right) .
$$

A differential system will be said conformally covariant if it can be written of the form $P_{g}(e)=f$, for a conformally covariant operator $P_{g}$.

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Erwann Delay, Laboratoire de Mathmatiques d'Avignon (EA 2151), F-84018 Avignon, France

E-mail address: Erwann.Delay@univ-avignon.fr
URL: http://www.univ-avignon.fr/fr/recherche/annuaire-chercheurs /membrestruc/personnel/delay-erwann-1.html

